

(a) Homogeneous Linear Equations of Second Order

A second order differential equation is called **linear** if it can be written as

$$\frac{d^2y}{dx^2} + p(x)\frac{dy}{dx} + q(x)y = r(x) \text{ or } y'' + p(x)y' + q(x)y = r(x)$$

and **nonlinear** if it cannot be written in this form.

The above equation is linear in the unknown function y and its derivatives, whereas p and q as well as r may be given function of x .

If $r(x) = 0$, then

$$y'' + p(x)y' + q(x)y = 0 \text{ is called homogeneous.}$$

If $r(x) \neq 0$, then

$$y'' + p(x)y' + q(x)y = r(x) \text{ is called nonhomogeneous.}$$

Fundamental Theorem for Homogeneous Equation

For a homogeneous linear differential equation any linear combination of two solutions is again a solution.

If y_1 and y_2 are solutions of homogeneous linear differential equation, then

$$y = c_1y_1 + c_2y_2 \text{ (Linear combination)}$$

is also a solution of the homogeneous linear differential equation.

Note: It does not hold for nonhomogeneous linear equations or nonlinear equations.

General Solution and Initial Value Problem

For second order homogeneous linear differential equations a general solutions is of the form

$$y = c_1y_1 + c_2y_2 \quad (c_1, c_2 \text{ are arbitrary constants})$$

An initial value problem now consists of

$$y'' + p(x)y' + q(x)y = 0 \text{ and two initial conditions } y(x_0) = K_0 \text{ and } y'(x_0) = K_1.$$

Using these conditions we can find constants c_1 and c_2 .

Basis

A basis of solutions is a pair y_1 and y_2 of linearly independent solutions.

Two functions $y_1(x)$ and $y_2(x)$ are linearly independent if

$$k_1 y_1(x) + k_2 y_2(x) = 0 \Rightarrow k_1 = 0, k_2 = 0.$$

and we call them linearly dependent if $k_1 y_1(x) + k_2 y_2(x) = 0$ for some constant k_1, k_2 not both zero.

If $k_1 \neq 0, k_2 \neq 0$, then $y_1 = -\frac{k_2}{k_1} y_2$ or $y_2 = -\frac{k_1}{k_2} y_1$.

How to Obtain Basis if One Solution is Known (Reduction of Order)

To get y_2 , set $y_2 = u y_1$. Then $y_2' = u' y_1 + u y_1'$ and $y_2'' = u'' y_1 + 2u' y_1' + u y_1''$.

Substituting y_2, y_2' and y_2'' in $y'' + p(x)y' + q(x)y = 0$

$$\Rightarrow u'' y_1 + 2u' y_1' + u y_1'' + p(u' y_1 + u y_1') y_2' + q u y_1 = 0$$

Collecting terms in u'', u' and u , we have

$$u'' y_1 + u'(2y_1' + p y_1) + u(y_1'' + p y_1' + q y_1) = 0$$

Since y_1 is a solution then $y_1'' + p y_1' + q y_1 = 0$.

$$\Rightarrow u'' y_1 + u'(2y_1' + p y_1) = 0 \Rightarrow u'' + u' \frac{2y_1' + p y_1}{y_1} = 0$$

Put $u' = U$ and $u'' = U'$ then

$$U' + \left(\frac{2y_1'}{y_1} + p \right) U = 0, \text{ this is the desired first-order equation.}$$

$$\Rightarrow \frac{dU}{U} = - \left(\frac{2y_1'}{y_1} + p \right) dx \Rightarrow \ln|U| = -2 \ln|y_1| - \int p dx \Rightarrow U = \frac{1}{y_1^2} e^{-\int p dx}$$

$$\therefore u' = U \Rightarrow u = \int U dx \Rightarrow y_2 = y_1 \int U dx$$

The quotient $\frac{y_2}{y_1} = u = \int U dx$ can not be constant (because $U \neq 0$), so that y_1 and y_2 form

a basis.