

3(b). The Divergence

The Operator $\vec{\nabla}$

The gradient has the formal appearance of a vector, $\vec{\nabla}$, “multiplying” a scalar V :

$$\vec{\nabla}V = \left(\hat{x}\frac{\partial}{\partial x} + \hat{y}\frac{\partial}{\partial y} + \hat{z}\frac{\partial}{\partial z} \right) V$$

The term in parentheses is called “del”:

$$\vec{\nabla} = \hat{x}\frac{\partial}{\partial x} + \hat{y}\frac{\partial}{\partial y} + \hat{z}\frac{\partial}{\partial z}$$

We should say that $\vec{\nabla}$ is a vector operator that acts upon V , not a vector that multiplies V .

There are three ways the operator $\vec{\nabla}$ can act:

1. on a scalar function V : $\vec{\nabla}V$ (the **gradient**);
2. on a vector function \vec{A} , via the dot product: $\vec{\nabla} \cdot \vec{A}$ (the **divergence**);
3. on a vector function \vec{A} , via the cross product: $\vec{\nabla} \times \vec{A}$ (the **curl**).

The Divergence

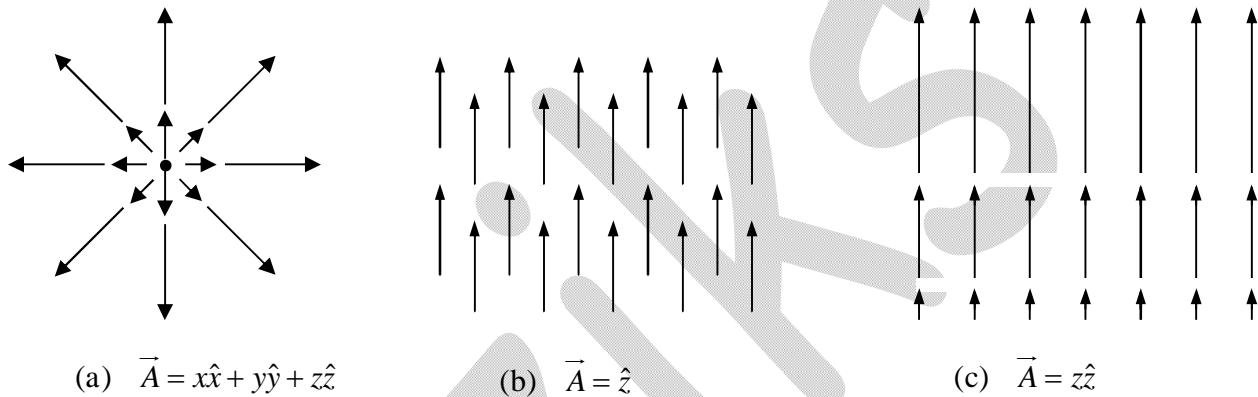
From the definition of $\vec{\nabla}$ we construct the divergence:

$$\vec{\nabla} \cdot \vec{A} = \left(\hat{x}\frac{\partial}{\partial x} + \hat{y}\frac{\partial}{\partial y} + \hat{z}\frac{\partial}{\partial z} \right) \cdot (A_x \hat{x} + A_y \hat{y} + A_z \hat{z}) = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

Observe that the divergence of a vector function \vec{A} is itself a scalar $\vec{\nabla} \cdot \vec{A}$. (You can't have the divergence of a scalar: that's meaningless.)

Geometrical Interpretation

$\vec{\nabla} \cdot \vec{A}$ is a measure of how much the vector \vec{A} spreads out (diverges) from the point in question. For example, the vector function in figure (a) has a large (positive) divergence (if the arrows pointed in, it would be a large negative divergence), the function in figure (b) has zero divergence, and the function in figure (c) again has a positive divergence. (Please understand that \vec{A} here is a function-there's a different vector associated with every point in space.)



Divergence in Spherical polar coordinates

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

Divergence in cylindrical coordinates

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

Example: Suppose the function sketched in above figure are $\vec{A} = x\hat{x} + y\hat{y} + z\hat{z}$, $\vec{B} = \hat{z}$ and $\vec{C} = z\hat{z}$. Calculate their divergences.

Solution: $\vec{\nabla} \cdot \vec{A} = \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) + \frac{\partial}{\partial z}(z) = 1 + 1 + 1 = 3$

$$\vec{\nabla} \cdot \vec{B} = \frac{\partial}{\partial x}(0) + \frac{\partial}{\partial y}(0) + \frac{\partial}{\partial z}(1) = 0 + 0 + 0 = 0$$

$$\vec{\nabla} \cdot \vec{C} = \frac{\partial}{\partial x}(0) + \frac{\partial}{\partial y}(0) + \frac{\partial}{\partial z}(z) = 0 + 0 + 1 = 1$$

Example: Given

(i) $\vec{A} = 2xy\hat{x} + z\hat{y} + yz^2\hat{z}$, find $\vec{\nabla} \cdot \vec{A}$ at $(2, -1, 3)$

(ii) $\vec{A} = 2r \cos^2 \phi \hat{r} + 3r^2 \sin z \hat{\phi} + 4z \sin^2 \phi \hat{z}$, find $\vec{\nabla} \cdot \vec{A}$

(iii) $\vec{A} = 10\hat{r} + 5 \sin \theta \hat{\theta}$, Find $\vec{\nabla} \cdot \vec{A}$

Solution: (i) In Cartesian coordinates $\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$

$$A_x = 2xy, A_y = z, A_z = yz^2 \Rightarrow \vec{\nabla} \cdot \vec{A} = 2y + 0 + 2yz, \text{ At } (2, -1, 3), \vec{\nabla} \cdot \vec{A} = -2 - 6 = -8$$

(ii) In cylindrical coordinates $\vec{\nabla} \cdot \vec{A} = \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$

$$A_r = 2r \cos^2 \phi, A_\phi = 3r^2 \sin z, A_z = 4z \sin^2 \phi$$

$$\Rightarrow \vec{\nabla} \cdot \vec{A} = \frac{1}{r} 4r \cos^2 \phi + 0 + 4 \sin^2 \phi = 4(\cos^2 \phi + \sin^2 \phi) = 4$$

(iii) In spherical coordinates, $\vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$

$$A_r = 10, A_\theta = 5 \sin \theta, A_\phi = 0$$

$$\Rightarrow \vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} 20r + \frac{1}{r \sin \theta} 10 \sin \theta \cos \theta = (2 + \cos \theta)(10/r)$$