

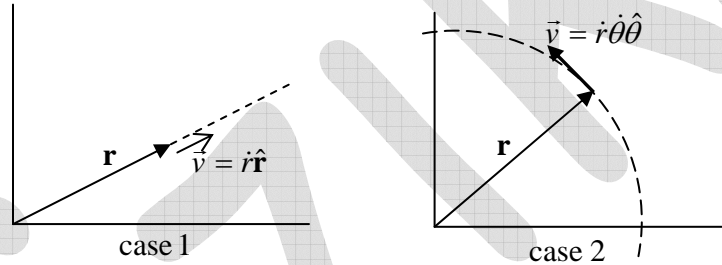
(b) Velocity and Acceleration in Polar Coordinate

1.1 The Position Vector in Polar Coordinate

$$\vec{r} = x\hat{i} + y\hat{j}, \vec{r} = |r|[\cos\theta\hat{i} + \sin\theta\hat{j}] \Rightarrow \vec{r} = |r|\hat{r}$$

$\mathbf{r} = r\hat{\mathbf{r}}$ is sometimes confusing, because the equation as written seems to make no reference to the angle θ . We know that two parameters needed to specify a position in two dimensional space (in Cartesian coordinates they are x and y), but the equation $\mathbf{r} = r\hat{\mathbf{r}}$ seems to contain only the quantity r . The answer is that $\hat{\mathbf{r}}$ is not a fixed vector and we need to know the value of θ to tell how $\hat{\mathbf{r}}$ is origin. Although θ does not occur explicitly in $r\hat{\mathbf{r}}$, its value must be known to fix the direction of $\hat{\mathbf{r}}$. This would be apparent if we wrote $\mathbf{r} = r\hat{\mathbf{r}}(\theta)$ to emphasize the dependence of $\hat{\mathbf{r}}$ on θ . However, by common conversation $\hat{\mathbf{r}}$ is understood to stand for $\hat{\mathbf{r}}(\theta)$.

1.2 Velocity Vector in Polar Coordinate



$$\vec{v} = \frac{d(r\hat{r})}{dt} = \frac{dr}{dt}\hat{r} + r\frac{d\hat{r}}{dt} = \dot{r}\hat{r} + r\frac{d\hat{r}}{dt} \Rightarrow \vec{v} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

where \dot{r} is radial velocity in \hat{r} direction and $r\dot{\theta}$ is tangential velocity in $\hat{\theta}$ direction as shown in figure and the magnitude to velocity vector $|\vec{v}| = \sqrt{\dot{r}^2 + r^2\dot{\theta}^2}$

1.3 Acceleration Vector in Polar Coordinate

$$\frac{d\vec{v}}{dt} = \frac{d\dot{r}}{dt}\hat{r} + \dot{r}\frac{d\hat{r}}{dt} + \frac{dr}{dt}\dot{\theta}\hat{\theta} + r\frac{d\dot{\theta}}{dt}\hat{\theta} + r\dot{\theta}\frac{d\hat{\theta}}{dt}$$

$$\frac{d\vec{v}}{dt} = \ddot{r}\hat{r} + \dot{r}\dot{\theta}\hat{\theta} + \dot{r}\dot{\theta}\hat{\theta} + r\ddot{\theta}\hat{\theta} + r\dot{\theta}(-\dot{\theta})\hat{r}$$

$$\vec{a} = (\ddot{r} - r\dot{\theta}^2)\hat{r} + (r\ddot{\theta} + 2\dot{r}\dot{\theta})\hat{\theta} \Rightarrow \vec{a} = a_r\hat{r} + a_\theta\hat{\theta}$$

$a_r = \ddot{r} - r\dot{\theta}^2$ is radial acceleration and $a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta}$ is tangential acceleration .

So Newton's law in polar coordinate can be written as

$$F_r = ma_r = m(\ddot{r} - r\dot{\theta}^2) \text{ where } F_r \text{ is external force in radial direction .}$$

$$F_\theta = ma_\theta = m(r\ddot{\theta} + 2\dot{r}\dot{\theta}) \text{ where } F_\theta \text{ is external force in tangential direction.}$$

Example: In planar polar co-ordinates, an object's position at time t is given as $(r, \theta) = (e^t m, \sqrt{8} t \text{ rad})$

(a) Find radial velocity tangential velocity and speed of particle at $t = 0$

(b) Find radial acceleration tangential acceleration and magnitude of acceleration at $t = 0$

Solution: (a) $(r, \theta) = (e^t m, \sqrt{8} t \text{ rad})$

$$r = e^t, \theta = \sqrt{8} t \text{ rad} \quad v_r = \dot{r} \Rightarrow v_r = e^t \text{ at } t = 0 \quad v_r = 1 \text{ m/sec}$$

$$\text{And } v_\theta = r\dot{\theta} \Rightarrow e^t \cdot \sqrt{8} \text{ at } t = 0 \quad v_\theta = r\dot{\theta} \Rightarrow e^t \cdot \sqrt{8} = \sqrt{8}$$

$$\text{Speed of particle is given by } |v| = \sqrt{v_r^2 + v_\theta^2} = \sqrt{(1)^2 + (\sqrt{8})^2} = \sqrt{9} = 3 \text{ m/sec}$$

(b) Magnitude of acceleration $a_r = \ddot{r} - \dot{\theta}^2 r \Rightarrow e^t - 8 \times e^t \text{ at } t = 0, 1 - 8 \times 1 = -7 \text{ m/sec}^2$

$$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta} \Rightarrow e^t \times 0 + 2e^t \sqrt{8} = 2\sqrt{8}$$

$$\text{Magnitude of acceleration is } |a| = \sqrt{(-7)^2 + 4 \times 8} = \sqrt{49 + 32} = \sqrt{81} = 9 \text{ m/sec}^2$$